

# Distributed Ray Tracing

© 1996-2018 Josef Pelikán  
CGG MFF UK Praha

pepca@cgg.mff.cuni.cz

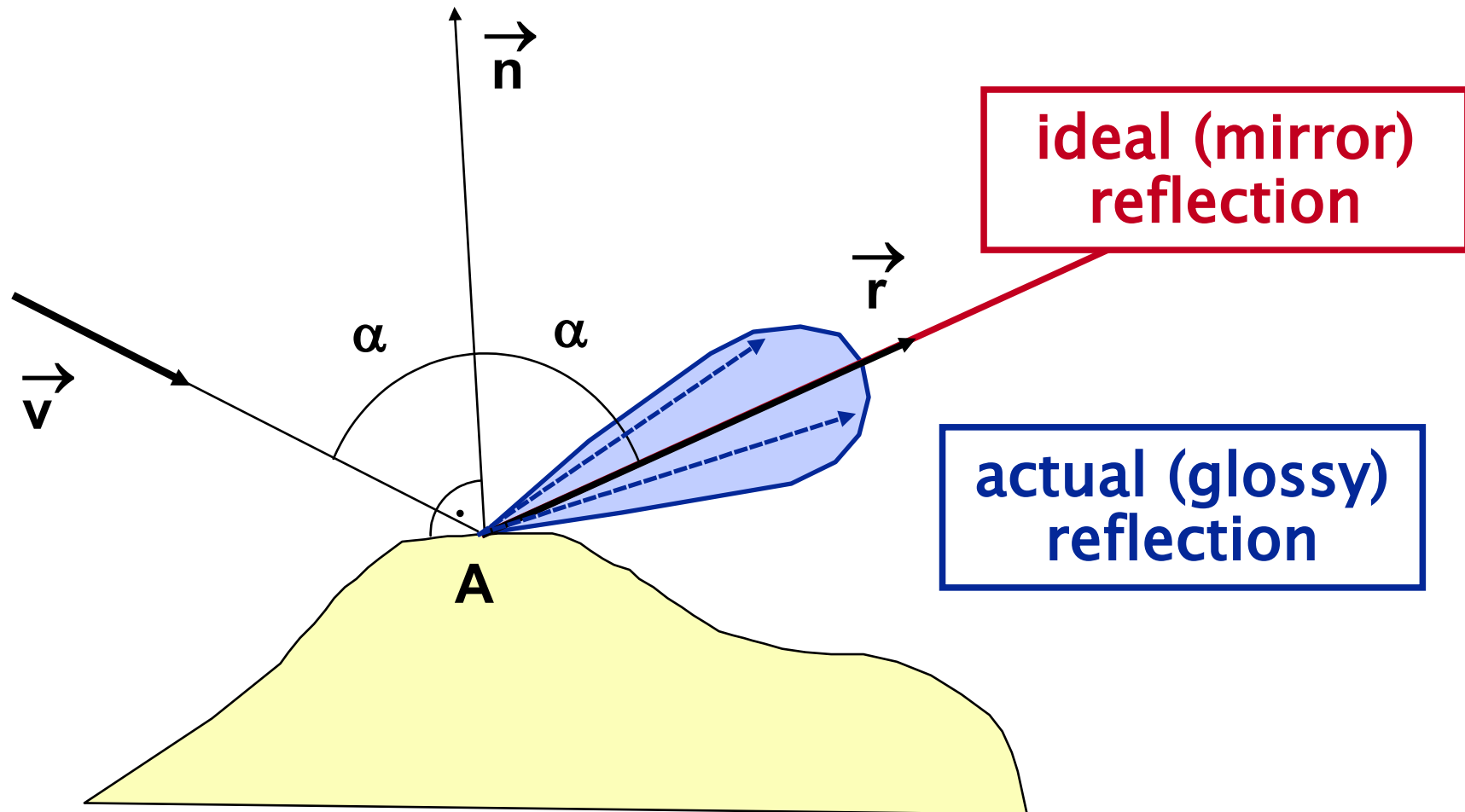
<http://cgg.mff.cuni.cz/~pepca/>



# Distributed ray tracing

- ♦ **better image quality** (fidelity)
  - soft shadows, glossy reflections, soft refractions
  - motion blur
  - depth of field imitation
  - light dispersion (index of refraction depends on  $\lambda$ )
- ♦ introducing **new variables** to an image function
  - reflection or refraction angle, wavelength, light source point, lens entry point, time, ..

# Glossy reflection





# Glossy reflection computation

Sharp reflection:

$$I(V) = I(R)$$

(one reflected ray)

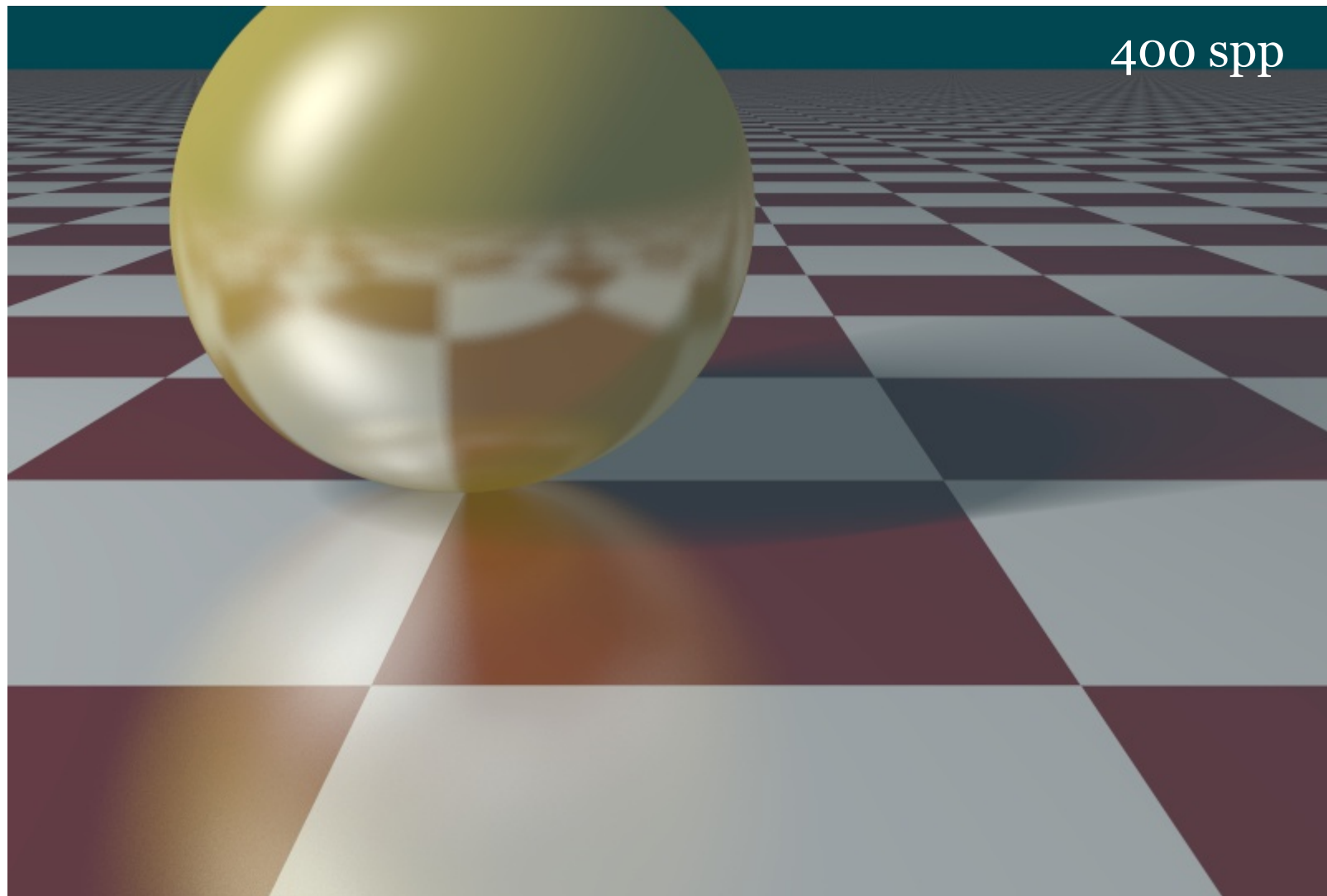
Glossy reflection:

$$I(V) = \iint_{\text{sphere}} I(R(\varphi, \theta)) \cdot \text{BRDF}(\alpha, \beta, \varphi, \theta) d\varphi d\theta$$

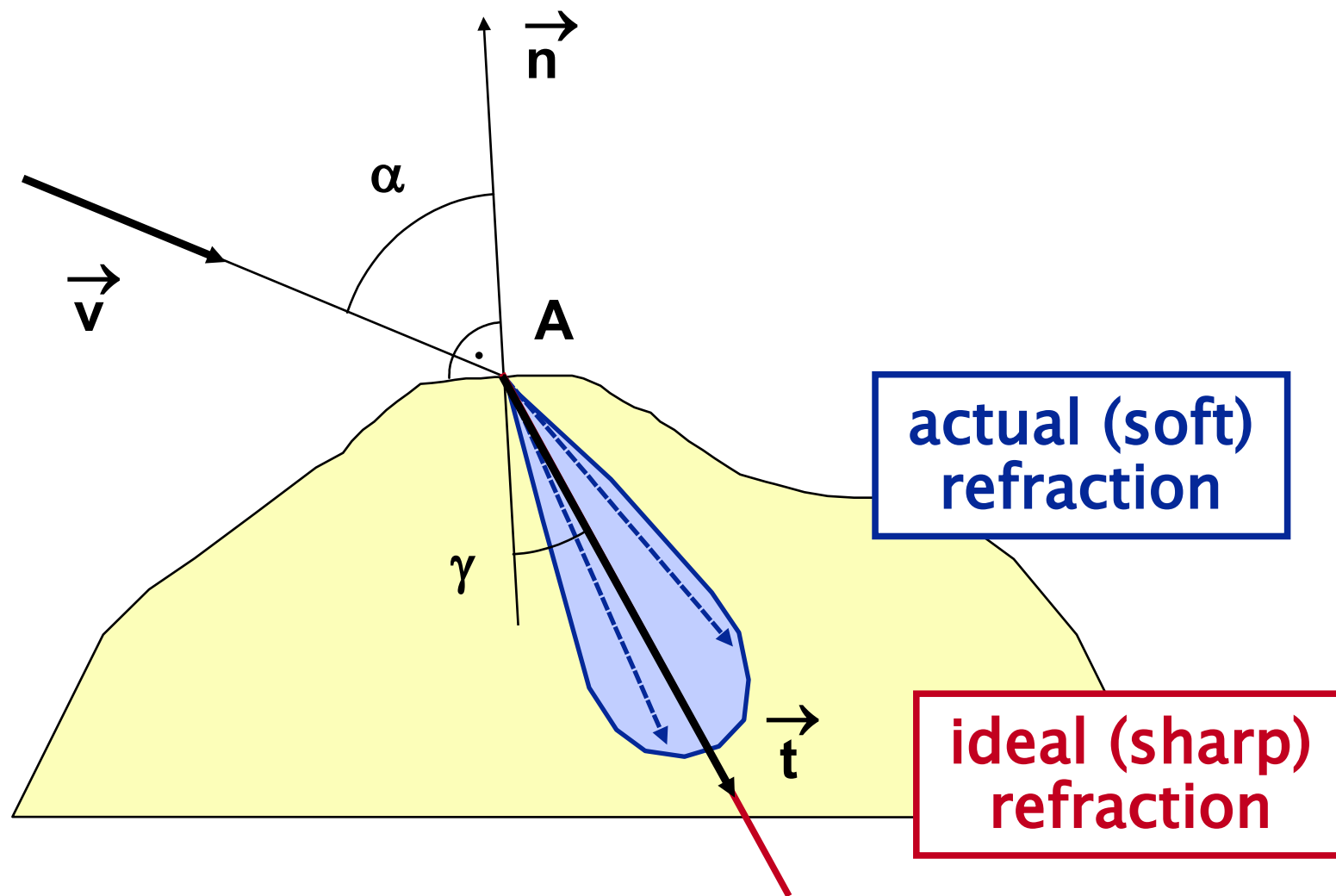
reflectance function

(weighted integral average .. over all reflection angles)

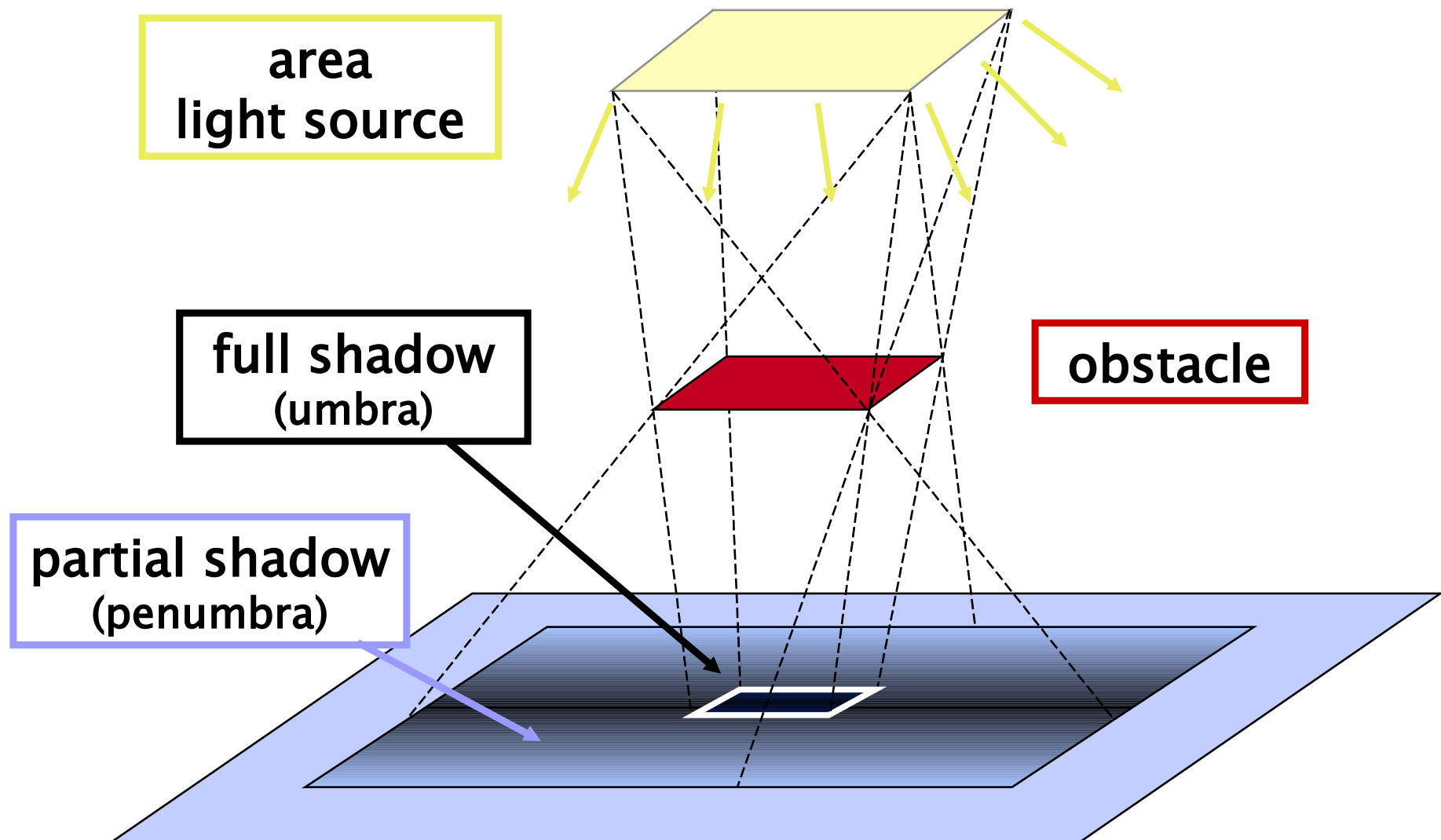
# Glossy reflection – example



# Soft refraction



# Soft shadow





# Soft shadow computation

Contribution of a point light source:

$$I(A) = \begin{cases} I_L & \text{if source is visible from } A \\ 0 & \text{else} \end{cases}$$

Contribution of an area light source:

$$I(A) = I_L \cdot S[\%]$$

visible portion of a light source





# Soft shadow computation

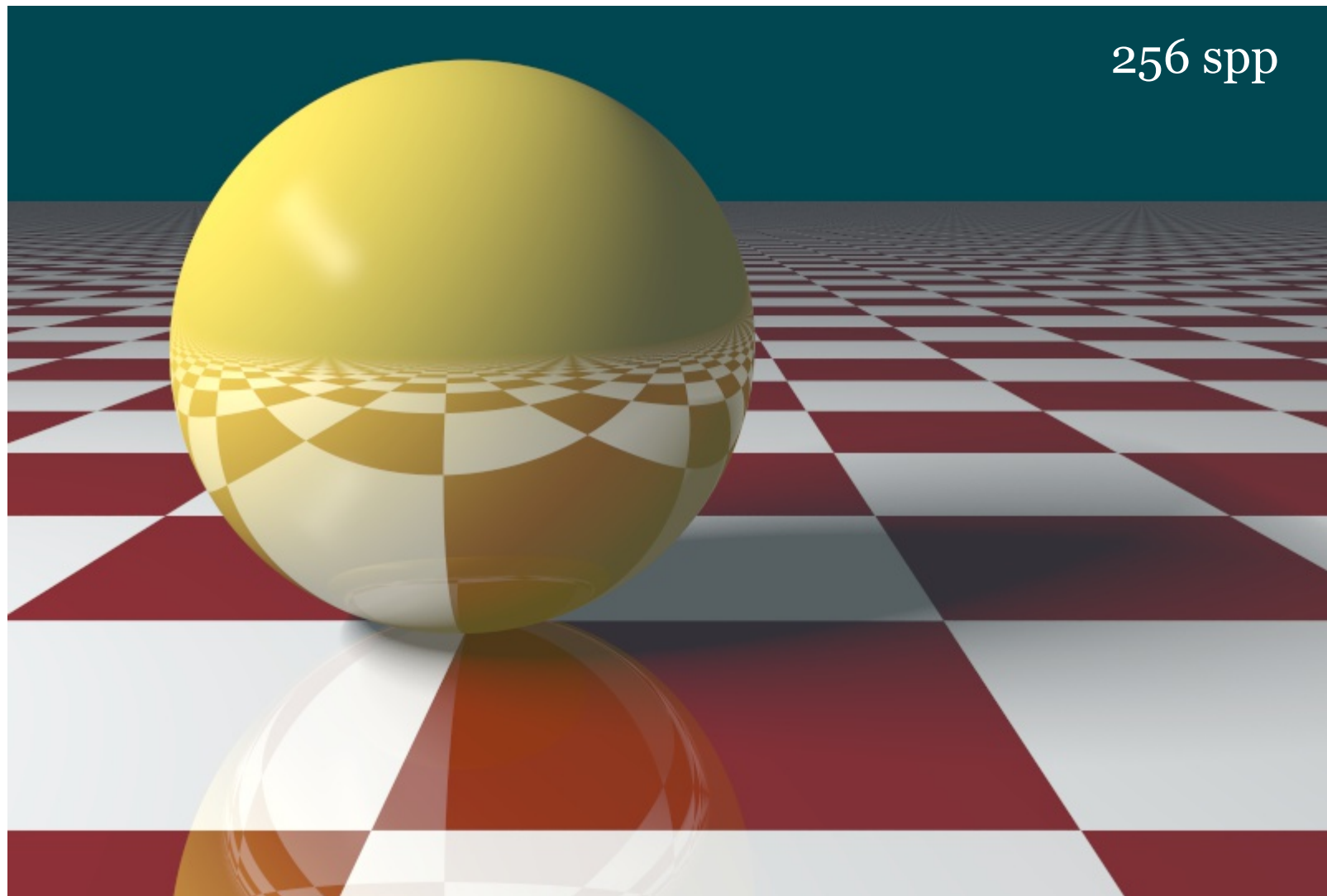
Contribution of an inhomogenous light source:

$$I(A) = \iint_{\text{light source area}} I_L(u, v) \cdot \underline{\text{vis}(A, u, v)} \, du \, dv$$

visibility function

$$\underline{\text{vis}(A, u, v)} = \begin{cases} 1 & \text{if } S(u, v) \text{ is visible from } A \\ 0 & \text{else} \end{cases}$$

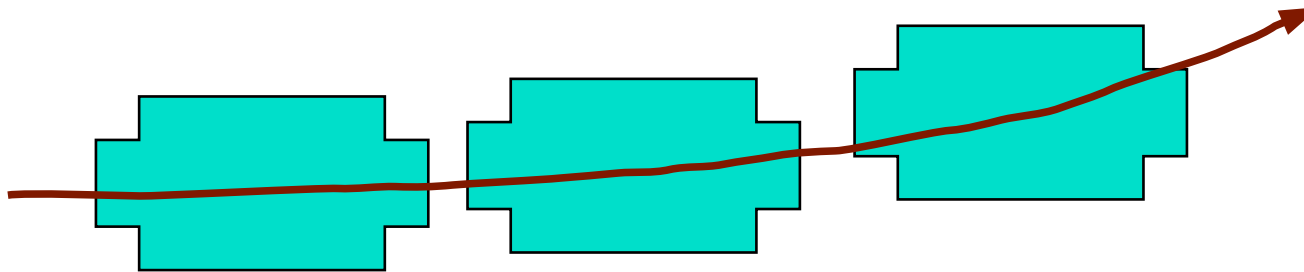
# Soft shadow – example





# Motion blur

path of the solid  $s(t)$



rendered interval:  
(shutter open time)

$[t_1, t_2]$

scene rendering in time  $t$ :

$f(t) = f(x, y, t)$

# Motion blur



**General motion blur:**

$$\mathbf{f}_{\text{blurr}} = \int_{t_1}^{t_2} \mathbf{f}(t) \, dt$$



# Motion blur

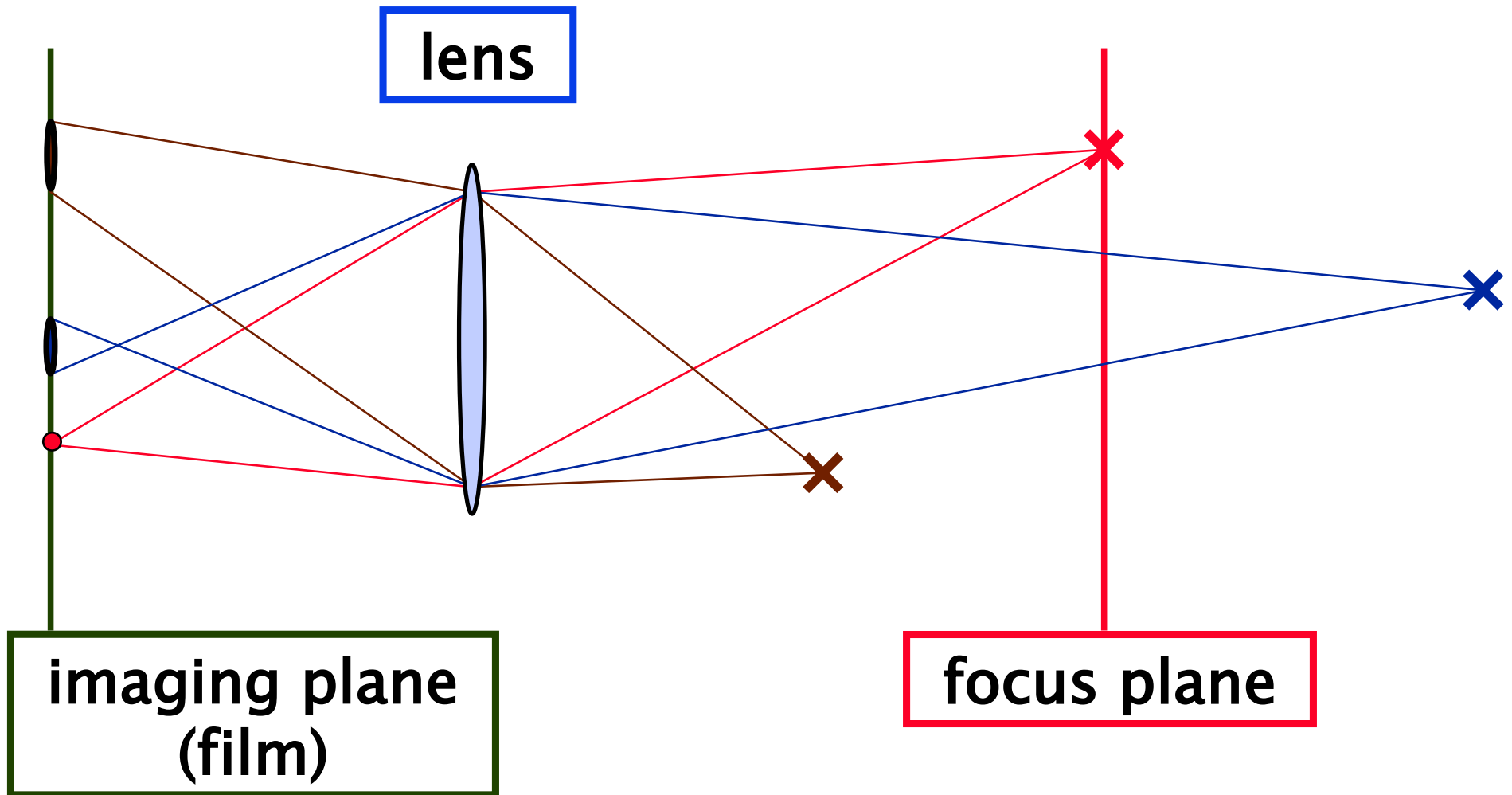
Scene with single moving object:

$$\mathbf{f}_{\text{blurr}} = \frac{\int_{t_1}^{t_2} \mathbf{f}(\mathbf{t}) \cdot |\mathbf{s}'(\mathbf{t})|^{-1} d\mathbf{t}}{\int_{t_1}^{t_2} |\mathbf{s}'(\mathbf{t})|^{-1} d\mathbf{t}}$$

$$|\mathbf{s}'(\mathbf{t})| \neq 0 \text{ on } \langle \mathbf{t}_1, \mathbf{t}_2 \rangle$$

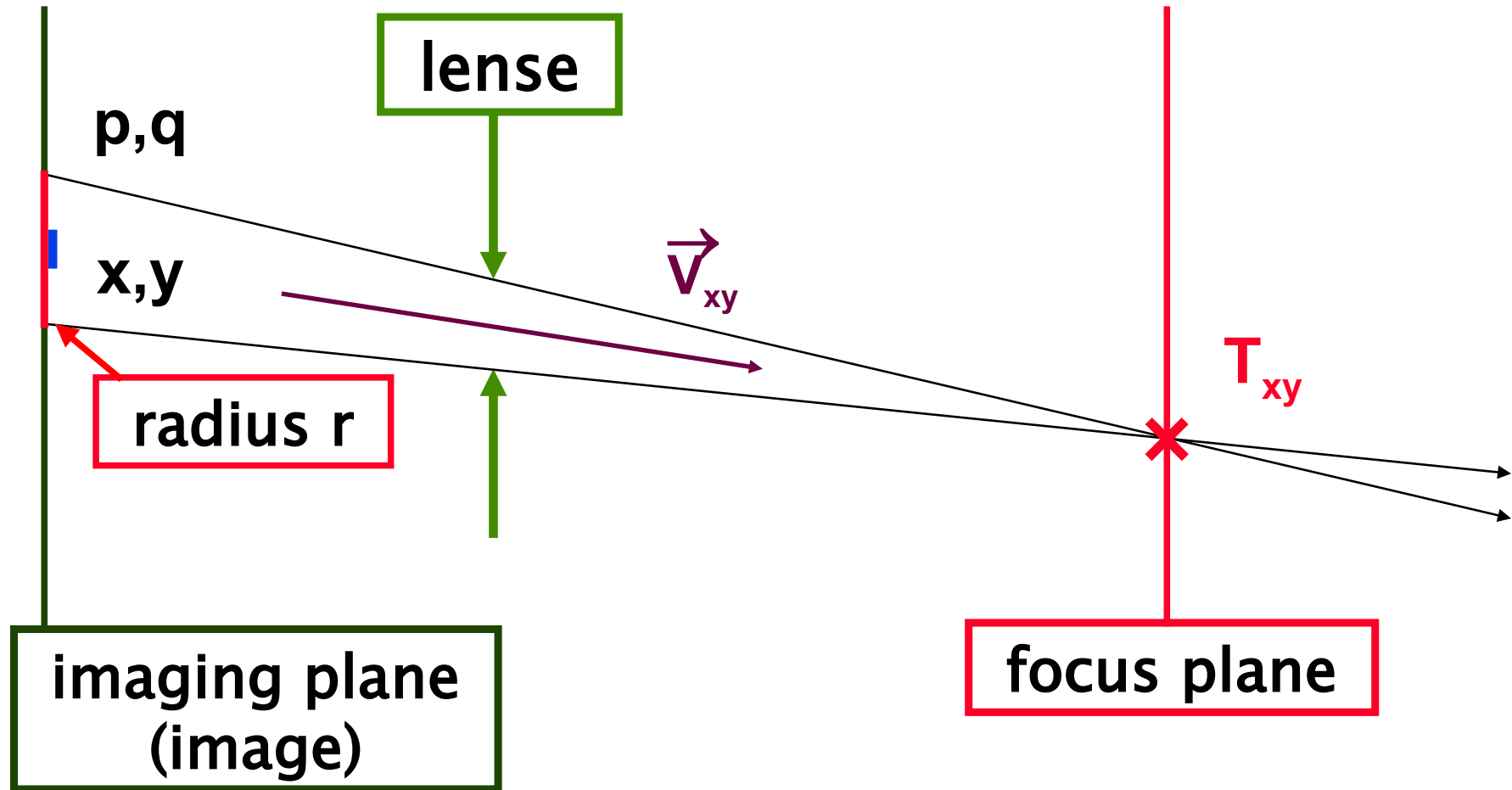


# Depth of field





# Geometric simplification





# Depth of field computation

Pinhole camera model:

$$f(\mathbf{x}, \mathbf{y}) = I(\mathbf{V}_{xy})$$

$$\mathbf{V}_{xy} = \mathbf{T}_{xy} - [\mathbf{x}, \mathbf{y}, 0]$$

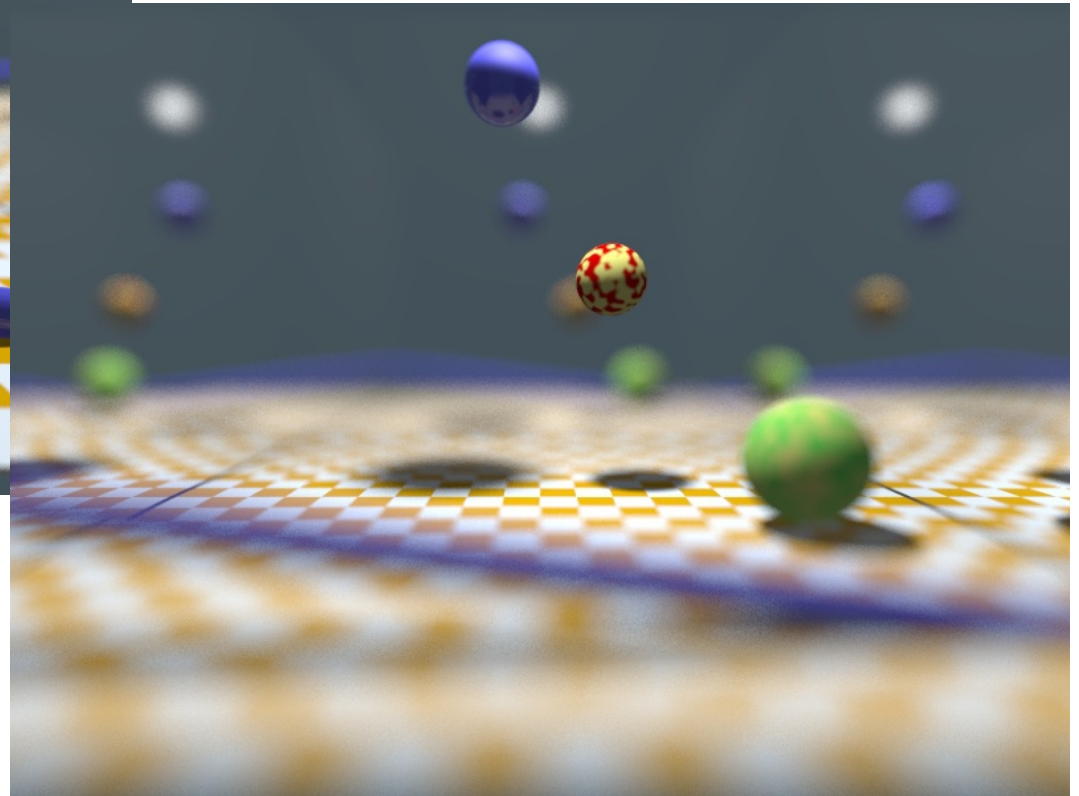
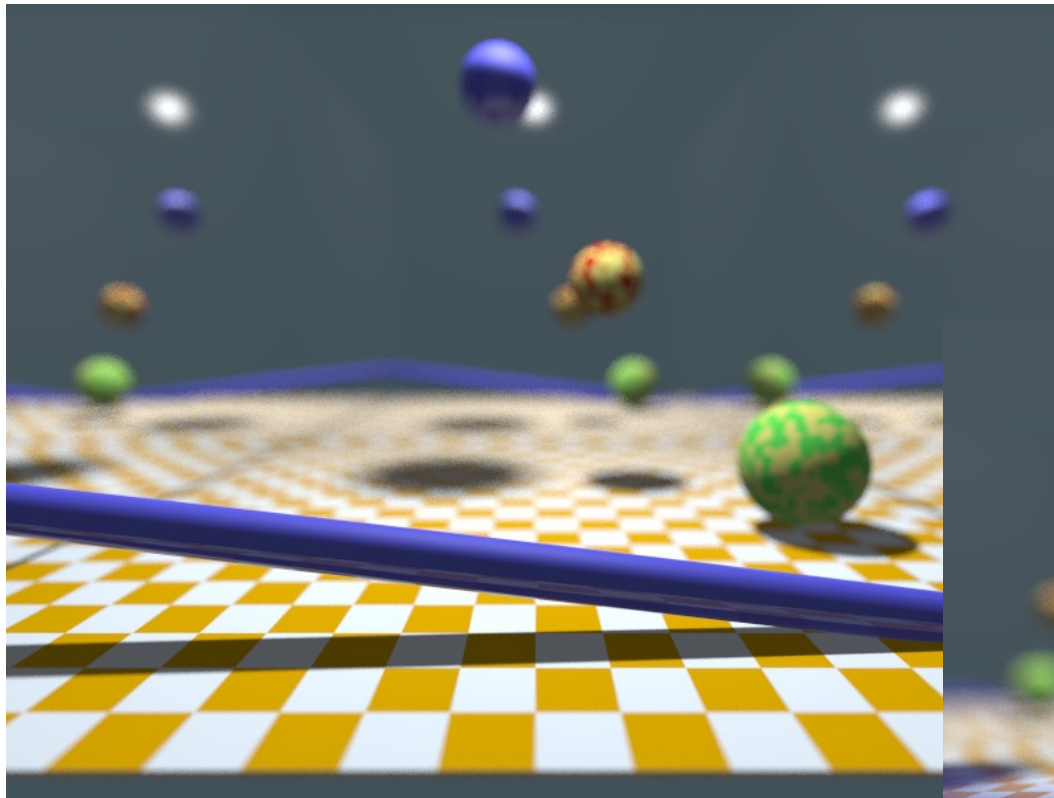
$$\mathbf{V}_{pq} = \mathbf{T}_{xy} - [\mathbf{p}, \mathbf{q}, 0]$$

Lens with finite aperture:

$$f(\mathbf{x}, \mathbf{y}) = \int_{\text{circle around } [\mathbf{x}, \mathbf{y}]} I(\mathbf{V}_{pq}) \, dp \, dq$$



# Depth of field – examples





# Light dispersion

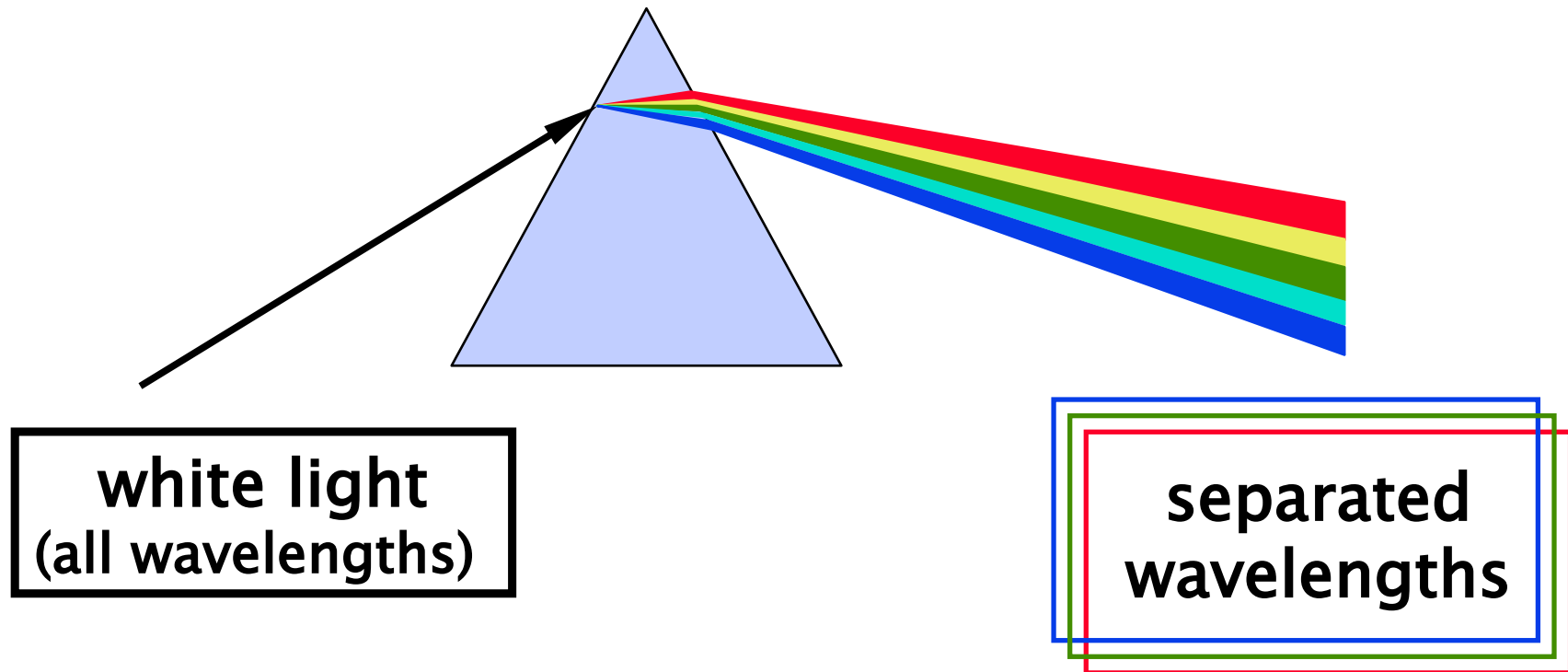


image function:  $f(\lambda) = f(x, y, \lambda)$



# Light dispersion computation

Pixel RGB color from spectral distribution:

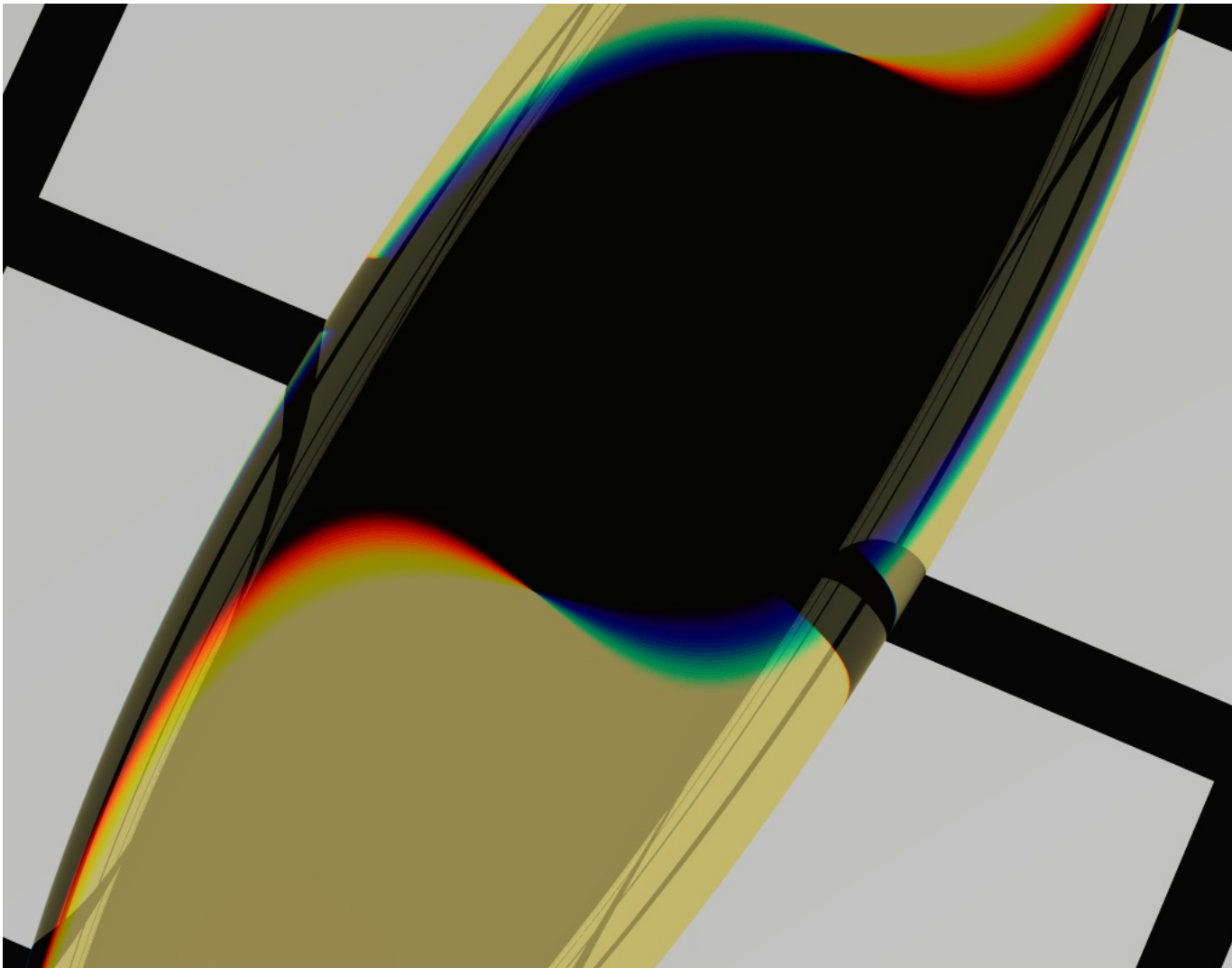
$$\mathbf{R}(\mathbf{x}, \mathbf{y}) = \int_{\text{spectrum}} \mathbf{f}(\mathbf{x}, \mathbf{y}, \lambda) \cdot \mathbf{R}(\lambda) d\lambda$$

$$\mathbf{G}(\mathbf{x}, \mathbf{y}) = \int_{\text{spectrum}} \mathbf{f}(\mathbf{x}, \mathbf{y}, \lambda) \cdot \mathbf{G}(\lambda) d\lambda$$

$$\mathbf{B}(\mathbf{x}, \mathbf{y}) = \int_{\text{spectrum}} \mathbf{f}(\mathbf{x}, \mathbf{y}, \lambda) \cdot \mathbf{B}(\lambda) d\lambda$$

trichromatic  
spectral  
coefficients

# Light dispersion – example





# Implementation

- ➔ integral averaging is done **stochastically** (Monte-Carlo methods)
  - finite number of point samples (rays)
  - integral is estimated by a [weighted] sum
- ➔ **weighted** integral average
  - uniform sampling and appropriate weight function
  - nonuniform sampling (using the right density/PDF)



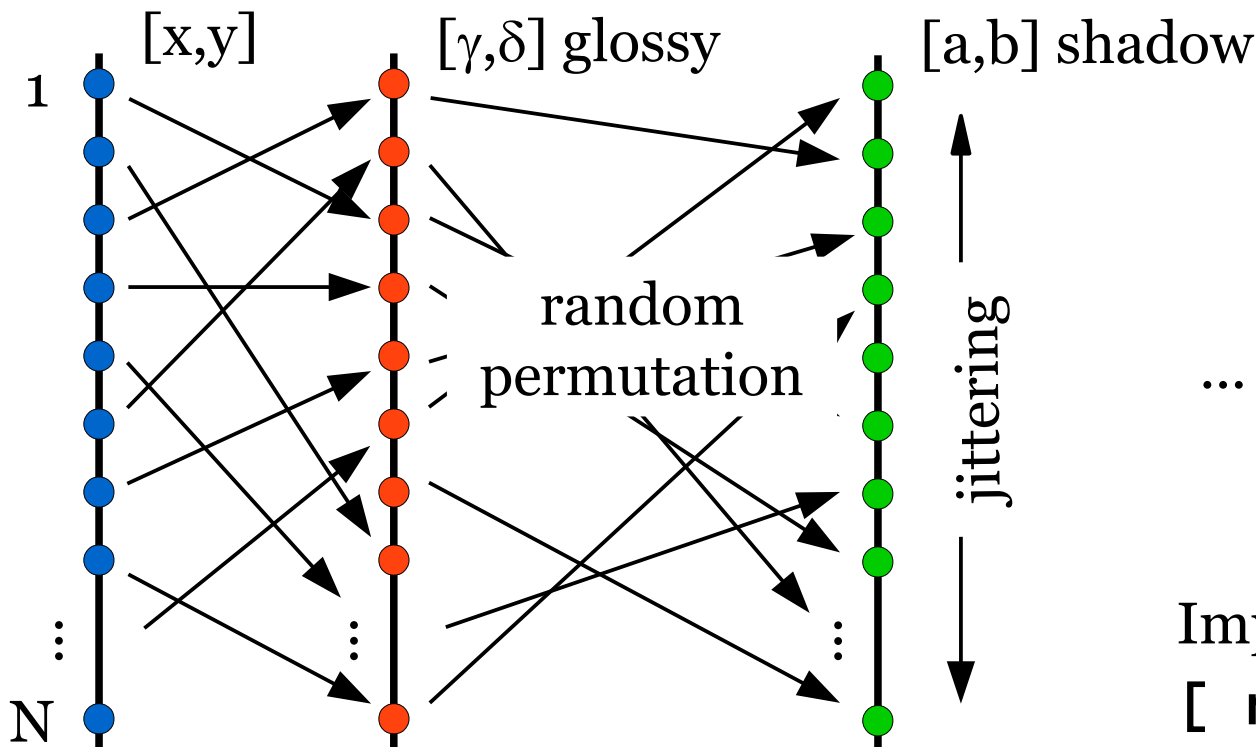
# Combining methods

- ➔ any methods can be **combined**
  - with anti-aliasing as well
  - higher order integrals – e.g. dimension 10:  
anti-aliasing (2), depth of field (2), glossy reflection (2),  
soft shadows (2), motion blur (1), light dispersion (1)
- ➔ **sampling method:**
  - jittering
  - independent jittering (“N rooks”) in form of **hidden sampling**
  - adaptive sampling



# Hidden sampling

- ➔ number of **samples per pix** (primary rays) is defined
  - every inner component is sampling independently
  - arbitrary number of additional (sampled) dimensions



Implementation:  
[ rank, total ]



# References

---

**A. Glassner: *An Introduction to Ray Tracing*,  
Academic Press, London 1989, 171-199**

**A. Watt, M. Watt: *Advanced Animation and  
Rendering Techniques*, Addison-Wesley,  
Wokingham 1992, 262-265**